# On Certain Types of Affine Motion 

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#### Abstract

In the present paper, the affine motion and the projective motion generated by recurrent in a general Finsler space is studied, the necessary and sufficient conditions for this projective motion to be affine motion are obtained. projective motion is studied in recurrent Finsler space.


Keywords: Finsler space; affine motion; projective motion; hv-curvature tensor $U_{j k h}^{i}$; U- recurrent space; Ubirecurrent space; projective recurrent space.

## 1. Introduction

K. Takano and T. Imai [15] studied certain types of affine motion generated by contra, concurrent, special concircular, recurrent, concircular, torse forming and birecurrent vector fields in a non-Riemannian space of recurrent curvature and ended with some remarks on the affine motion in a space with recurrent curvature. K. Takano and T. Imai [15], P. N. Pandey and V. J. Dwivedi [8] further wrote a series of three papers on the existence affine motion in a non-Riemannian space of recurrent curvature and obtained various interesting results. K. Takan and T. Imai [15] and S. P. Singh [14] discussed the affine motion in a birecurrent nonRiemannian space.

[^0]Several results obtained by these authors were extended to Finsler spaces of recurrent curvature by R. B. Misra [6], F. M. Meher [5], A. Kumar ([1], [2], [3]), A. Kumar, H. S. Shukla and R. P. Tripathi [4], P. N. Pandey, F. Y. A. Qasem and Suinta Pal [9], S. P. Singh [13] and others. K. Yano [16] defined the normal projective connection coefficients $\Pi_{j k}^{i}$ by

$$
\begin{equation*}
\Pi_{j k}^{i}=G_{j k}^{i}-y^{i} G_{j k r}^{r} \tag{1.1}
\end{equation*}
$$

The connection coefficients $\Pi_{j k}^{i}$ is positively homogeneous of degree zero in $y^{i}$ 's and symmetric in their lower indices and the normal projective tensor $N_{j k h}^{i}$ is defined as follows [16]:

$$
\begin{equation*}
N_{j k h}^{i}=\Pi_{j k h}^{i}+\Pi_{r j h}^{i} \Pi_{k s}^{r} y^{s}+\Pi_{r h}^{i} \Pi_{k j}^{r}-k \mid h, \tag{1.2}
\end{equation*}
$$

where

$$
\begin{equation*}
\Pi_{j k h}^{i}=\dot{\partial}_{j} \Pi_{k h}^{i} \tag{1.3}
\end{equation*}
$$

$\Pi_{j k h}^{i}$ constitutes the components of a tensor.

Remark 1.1. K. Yano [16] denoted the tensor $\prod_{j k h}^{i}$ by the curvature tensor $U_{j k h}^{i}$.

The curvature tensor $U_{j k h}^{i}$ is defined by

$$
\begin{equation*}
U_{j k h}^{i}=G_{j k h}^{i}-\frac{1}{n+1}\left(\delta_{j}^{i} G_{j k r}^{r}+y^{i} G_{j k h r}^{r}\right) \tag{1.4}
\end{equation*}
$$

is called hv-curvature tensor, where $G_{j k h}^{i}$ is connection of hv-curvature tensor. Also this tensor satisfy the following:

$$
\begin{equation*}
U_{j k h}^{i} y^{j}=0 \tag{1.5}
\end{equation*}
$$

We also have the following commutation formulae [12]

$$
\begin{equation*}
\left(\dot{\partial}_{j} \mathcal{B}_{k}-\mathcal{B}_{k} \dot{\partial}_{j}\right) X^{i}=U_{j k h}^{i} X^{h}-\left(\dot{\partial}_{r} X^{i}\right) U_{j k h}^{r} y^{h} \tag{1.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathcal{B}_{k} \mathcal{B}_{h} T_{j}^{i}-\mathcal{B}_{h} \mathcal{B}_{k} T_{j}^{i}=T_{j}^{r} \mathrm{~N}_{r k h}^{i}-T_{r}^{i} \mathrm{~N}_{j k h}^{r}-\left(\dot{\partial}_{r} T_{j}^{i}\right) \mathrm{N}_{s k h}^{r} y^{s} . \tag{1.7}
\end{equation*}
$$

A Finsler space is called recurrent Finsler space and birecurrent Finsler space, respectively, denoted them by $U R-F_{n}$ and $U B R-F_{n}$, respectively, if it's hv- curvature tensor $U_{j k h}^{i}$ satisfies ([10], [11])

$$
\begin{equation*}
\mathcal{B}_{m} U_{j k h}^{i}=\lambda_{m} U_{j k h}^{i}, \quad U_{j k h}^{i} \neq 0 \tag{1.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathcal{B}_{l} \mathcal{B}_{m} U_{j k h}^{i}=a_{m l} U_{j k h}^{i}, \quad U_{j k h}^{i} \neq 0, \tag{1.9}
\end{equation*}
$$

where $\lambda_{m}$ and $a_{l m}$ are non-zero covariant vector and tensor fields.

Let us consider a transformation

$$
\begin{equation*}
\bar{x}^{i}=x^{i}+\varepsilon v^{i}\left(x^{j}\right) \tag{1.10}
\end{equation*}
$$

where $\varepsilon$ is an infinitesimal constant and $v^{i}\left(x^{j}\right)$ is called contravariant vector filed independent of $y^{i}$. The transformation represented by (1.10) is called an infinitesimal transformation. Also this transformation gives rise to a process of differentiation called

Lie- differentiation.

Let $X^{i}$ be an arbitrary contravariant vector filed. Its Lie-derivative with respect to the above infinitesimal transformation is given by ([12], [16])

$$
\begin{equation*}
L_{v} X^{i}=v^{r} \mathcal{B}_{r} X^{i}-X^{r} \mathcal{B}_{r} v^{i}+\left(\dot{\partial}_{r} X^{i}\right) \mathcal{B}_{s} v^{r} y^{s} \tag{1.12}
\end{equation*}
$$

where the symbol $L_{v}$ stands for the Lie- differentiation. In view of (1.12), Lie-derivatives of $y^{i}$ and $v^{i}$ with respect to above infinitesimal transformation vanish, i.e.
a) $L_{v} y^{i}=0$
and
b) $L_{v} v^{i}=0$.

Lie-derivative an of arbitrary tensor $T_{j}^{i}$ with respect to the above infinitesimal transformation is given by

$$
\begin{equation*}
L_{v} T_{j}^{i}=v^{r} \mathcal{B}_{r} T_{j}^{i}-T_{j}^{r} \mathcal{B}_{r} v^{i}+T_{r}^{i} \mathcal{B}_{j} v^{r}+\left(\dot{\partial}_{r} T_{j}^{i}\right) \mathcal{B}_{s} v^{r} y^{s} . \tag{1.14}
\end{equation*}
$$

Lie-derivative of the normal projective connection parameters $\Pi_{j k}^{i}$ is given by [16]

$$
\begin{equation*}
L_{v} \Pi_{j k}^{i}=\mathcal{B}_{j} \mathcal{B}_{k} v^{i}-U_{r j k}^{i} y^{s} \mathcal{B}_{s} v^{r}+N_{r j k}^{i} v^{r} . \tag{1.15}
\end{equation*}
$$

The commutation formulae for the operators $\mathcal{B}_{k}, \dot{\partial}_{j}$ and $L_{v}$ are given by

$$
\begin{equation*}
\left(L_{v} \mathcal{B}_{k}-\mathcal{B}_{k} L_{v}\right) X^{i}=X^{h} L_{v} \Pi_{k h}^{i}-\left(\dot{\partial}_{r} X^{r}\right) L_{v} \Pi_{k h}^{i} y^{h} \tag{1.16}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(\dot{\partial}_{j} L_{v}-L_{v} \dot{\partial}_{j}\right) X^{i}=0 . \tag{1.17}
\end{equation*}
$$

where $X^{i}$ is a contravariant vector filed.

The necessary and sufficient condition for the transformation (1.10) to be a motion, affine motion and projective motion are respectively given by

$$
\begin{equation*}
L_{v} g_{i j}=0 \tag{1.18}
\end{equation*}
$$

$$
\begin{equation*}
L_{v} \Pi_{k h}^{i}=0 \tag{1.19}
\end{equation*}
$$

and

$$
\begin{equation*}
L_{v} \Pi_{j k}^{i}=\delta_{j}^{i} P_{k}+\delta_{k}^{i} P_{j}, \tag{1.20}
\end{equation*}
$$

where $P_{j}$ is defined as

$$
\begin{equation*}
P_{j}=\dot{\partial}_{j} P \tag{1.21}
\end{equation*}
$$

P being a scalar, positively homogeneous of degree one in $y^{i}$.

It is well know that every motion is affine motion and every affine motion is a projective motion. A projective motion need not be affine motion.

## 2. Affine motion

Let an infinitesimal transformation (1.10) be generated by a vector filed $v^{i}\left(x^{j}\right)$.The
infinitesimal transformation is an affine motion if and if Lie - derivative of the normal
projective connection parameters $\Pi_{j k}^{i}$ with respect to infinitesimal transformation (1.10) vanishes identically, i.e. $L_{v} \Pi_{j k}^{i}=0$.

The vector filed $v^{i}\left(x^{j}\right)$ is called contra, concurrent, special concircular, recurrent and torse forming according as it satisfies
a) $\mathcal{B}_{k} v^{i}=0$,
b) $\mathcal{B}_{k} v^{i}=c \delta_{k}^{i}, \quad$ c being a constant,
c) $\mathcal{B}_{k} v^{i}=\rho \delta_{k}^{i}, \quad \rho$ is not a constant,
d) $\mathcal{B}_{k} v^{i}=\mu_{k} v^{i}$
and
e) $\mathcal{B}_{k} v^{i}=\mu_{k} v^{i}+\rho \delta_{k}^{i}$,
respectively. The affine motion generated by above vectors is called contra affine motion, concurrent affine motion, special concircular affine motion, recurrent affine motion and torse forming affine motion, respectively.

## 3. Contra Affine Motion

Let us consider an infinitesimal transformation generated by contra vector $v^{i}\left(x^{j}\right)$ characterized by (2.1a).

Differentiating (2.1a) covariantly with respect to $x^{j}$ in the sense of Berwald, we get
(3.1) $\quad \mathcal{B}_{j} \mathcal{B}_{k} v^{i}=0$.

Taking skew-symmetric part of (3.1), using the commutation formula exhibited by (1.7) for $v^{i}$, we get
(3.2) $\quad N_{h j k}^{i} v^{h}=0$.

Using (3.1), (2.1a) and (3.2) in (1.15), we get

$$
\begin{equation*}
L_{v} \Pi_{j k}^{i}=0 \tag{3.3}
\end{equation*}
$$

Hence the infinitesimal transformation considered is an affine motion.

Thus, we conclude

Theorem 3.1. Every contra vector generates an affine motion in a Finsler space.

Thus, we conclude

Corollary 3.1. Every contra vector generates a projective motion.

Theorem 3.2. In an $U R-F_{n}$, if any contra vector $v^{i}\left(x^{j}\right)$ generates an infinitesimal transformation, it must be orthogonal to the recurrence vector.
proof

Let us consider an $U R-F_{n}$ and a contra vector $\mathrm{v}^{\mathrm{i}}\left(\mathrm{x}^{\mathrm{j}}\right)$ characterized by (1.8) and (2.1a), respectively. Then, the hv-curvature tensor $U_{j k h}^{i}$ satisfies $L_{v} U_{h j k}^{i}=0$.

In view of (1.14) and (2.1a), we get

$$
\begin{equation*}
L_{v} U_{j k h}^{i}=v^{r} \mathcal{B}_{r} U_{j k h}^{i} . \tag{3.4}
\end{equation*}
$$

Differentiating (3.3) partially with respect to $y^{h}$, we get

$$
\begin{equation*}
\dot{\partial}_{h} L_{v} \Pi_{j k}^{i}=0 \tag{3.5}
\end{equation*}
$$

Taking skew-symmetric part of (3.5), using the commutation formula exhibited by (1.17) for $\Pi_{j k}^{i}$, (3.5) in view of remark 1.1., we get

$$
\begin{equation*}
L_{v} U_{h j k}^{i}=0 . \tag{3.6}
\end{equation*}
$$

In view of (3.4) and (3.6), we get

$$
\begin{equation*}
v^{r} \mathcal{B}_{r} U_{j k h}^{i}=0 . \tag{3.7}
\end{equation*}
$$

Transvecting (1.8) by $v^{m}$ and using (3.7), we get

$$
\begin{equation*}
v^{m} \lambda_{m}=0, \tag{3.8}
\end{equation*}
$$

where $U_{j k h}^{i} \neq 0$.

Thus, we see that the contra vector $\mathrm{v}^{\mathrm{i}}\left(\mathrm{x}^{\mathrm{j}}\right)$ is orthogonal to the recurrence vector $\lambda_{m}$.

Theorem 3.3. In an $U B R-F_{n}$, if any contra vector $v^{i}\left(x^{j}\right)$ generates an infinitesimal transformation, then the recurrence tensor $a_{l m}$ satisfies
a) $a_{m l} v^{m}=0$
and
b) $v^{m} a_{l m}=0$.
proof

Let us consider an $U B R-F_{n}$ and a contra vector $\mathrm{v}^{\mathrm{i}}\left(\mathrm{x}^{\mathrm{j}}\right)$ characterized by (1.9) and (2.1a), respectively. Then, the hv-curvature tensor $U_{j k h}^{i}$ satisfies $L_{v} U_{h j k}^{i}=0$.

Differentiating (3.7) covariantly with respect to $x^{l}$ in the sense of Berwald, using (2.1a) and (1.9), we get

$$
\begin{equation*}
a_{m l} v^{m}=0, \tag{3.10}
\end{equation*}
$$

where $U_{j k h}^{i} \neq 0$, it's the equ. (3.9a).

Taking skew-symmetric part of (3.10), we get

$$
\begin{equation*}
\left(a_{m l}-a_{l m}\right) v^{m}=0, \tag{3.11}
\end{equation*}
$$

where $U_{j k h}^{i} \neq 0$.

Using (3.9a) in (3.11), we get
(3.12) $\quad a_{l m} v^{m}=0$
which its equ. (3.9b).

## 4. Concurrent Affine Motion

Let us consider an infinitesimal transformation generated by concurrent vector $v^{i}\left(x^{j}\right)$ characterized by (2.1b).

Differentiating (2.1b) covariantly with respect to $x^{j}$ in the sense of Berwald, we get (3.1). Taking skewsymmetric part of (3.1), using the commutation formula exhibited by (1.7) for $v^{i}$, we get (3.2). Using (3.1), (2.1a) and (3.2) in (1.15), we get (3.3). Hence the infinitesimal transformation considered is an affine motion. Thus, we conclude

Theorem 4.1. If a Finsler space admits an infinitesimal transformation generated by a concurrent vector , then the transformation is necessarily an affine motion.

In view of (3.6) and (1.14), we get

$$
\begin{align*}
& v^{r} \mathcal{B}_{r} U_{j k h}^{i}-U_{j k h}^{r} \mathcal{B}_{r} v^{i}+U_{r k h}^{i} \mathcal{B}_{j} v^{r}+U_{j r h}^{i} \mathcal{B}_{k} v^{r}+U_{j k r}^{i} \mathcal{B}_{h} v^{r}  \tag{4.1}\\
& \quad+\left(\dot{\partial}_{r} U_{j k h}^{i}\right) \mathcal{B}_{s} v^{r} y^{s}=0 .
\end{align*}
$$

Using (2.1b) in (4.1), we get

$$
\begin{equation*}
v^{m} \mathcal{B}_{m} \mathrm{U}_{j k h}^{i}+2 c U_{j k h}^{i}=0 . \tag{4.2}
\end{equation*}
$$

Differentiating (4.2) covariantly with respect to $x^{l}$ in the sense of Berwald and using (2.1b), we get

$$
\begin{equation*}
v^{m} \mathcal{B}_{l} \mathcal{B}_{m} U_{j k h}^{i}+3 c \mathcal{B}_{l} U_{j k h}^{i}=0 . \tag{4.3}
\end{equation*}
$$

Thus, we conclude

Theorem 4.2. If a Finsler space admits an infinitesimal transformation generated by a concurrent vector, then the $h v$-curvature tensor $U_{j k h}^{i}$ satisfies (4.2) and (4.3).

If the space an $U R-F_{n}$, which is characterized by (1.8), is symmetric and denoted by $S U R-F_{n}$.Thus, the $S U R-F_{n}$ is characterized by

$$
\begin{equation*}
\mathcal{B}_{m} U_{j k h}^{i}=0 . \tag{4.4}
\end{equation*}
$$

In view of (4.2) and (4.4), we get $c \mathrm{U}_{j k h}^{i}=0$, which implies $U_{j k h}^{i}=0$ for $c \neq 0$.

Thus, we see that a symmetric recurrent space admitting an infinitesimal transformation generated by a concurrent vector is necessarily flat ${ }^{*}$.

Thus, we conclude

Corollary 4.1. A non-flat $S U R-F_{n}$ does not admit any infinitesimal transformation generated by a concurrent vector.

If the space $U B R-F_{n}$, which is characterized by (1.9), is bisymmetric and denoted by
$S U B R-F_{n}$. Thus, the $S U B R-F_{n}$ is characterized by

$$
\begin{equation*}
\mathcal{B}_{l} \mathcal{B}_{m} \mathrm{U}_{j k h}^{i}=0 \tag{4.5}
\end{equation*}
$$

In view of (4.2), (4.3) and (4.5), we get $c U_{j k h}^{i}=0$, which implies $U_{j k h}^{i}=0$ for $c \neq 0$. Thus, we see that a bisymmetric space admitting an infinitesimal transformation generated by a concurrent vector is necessarily flat.

Thus, we conclude

Corollary 4.2. A non-flat $S U B R-F_{n}$ does not admit any infinitesimal transformation generated by a concurrent vector.

## 5. Special Concircular Affine Motion

Let us consider an infinitesimal transformation generated by concurrent vector $v^{i}\left(x^{j}\right)$ characterized by (2.1c).

Hence, the infinitesimal transformation considered is an affine motion, we get $L_{v} \Pi_{j k}^{i}=0$.

In view of (1.15), (1.19), (2.1c), (1.5) and (3.2), we get

$$
\begin{equation*}
\mathcal{B}_{j} \rho \delta_{k}^{i}=0 . \tag{5.1}
\end{equation*}
$$

Transvecting (5.1) by $y^{k}$ and using the fact $\left(\mathcal{B}_{j} y^{k}=0\right)$, we get

$$
\begin{equation*}
y^{i} \mathcal{B}_{j} \rho=0 . \tag{5.2}
\end{equation*}
$$

Transvecting (5.2) by $y_{i}$ and using the fact $\left(y^{i} y_{i}=F^{2}\right)$, we get

$$
\begin{equation*}
F^{2} \mathcal{B}_{j} \rho=0 \tag{5.3}
\end{equation*}
$$

which implies $\mathcal{B}_{j} \rho=0$, a contradiction

Thus, we conclude

Theorem 5.1. A Finsler space does not admit any special concircular affine motion

A Finsler space with vanishing hv-curvature tensor is called flat.

## 6. Recurrent Affine Motion

Let us consider an infinitesimal transformation generated by concurrent vector $v^{i}\left(x^{j}\right)$ characterized by (2.1d)

Differentiating (2.1d) covariantly with respect to $x^{j}$ in the sense of Berwald and using (2.1d), we get

$$
\begin{equation*}
\mathcal{B}_{j} \mathcal{B}_{k} v^{i}=\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i} . \tag{6.1}
\end{equation*}
$$

In view of (1.15), (6.1), (2.1d) and putting $\mu=\mu_{h} y^{h}$, we get

$$
\begin{equation*}
L_{v} \Pi_{j k}^{i}=\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i}-\mu U_{r j k}^{i} v^{r}+N_{r j k}^{i} v^{r} \tag{6.2}
\end{equation*}
$$

Differentiating (2.1d) partially with respect to $y^{j}$, we get

$$
\begin{equation*}
\dot{\partial}_{j} \mathcal{B}_{k} v^{i}=\dot{\partial}_{j}\left(\mu_{k} v^{i}\right) \tag{6.3}
\end{equation*}
$$

Transvecting (4.1) by $y^{j}$, using the fact ( $\mathcal{B}_{r} y^{i}=0$ ), (1.5), (2.1d) and putting $\mu=\mu_{t} y^{t}$, , we get

$$
\begin{equation*}
U_{r k h}^{i} v^{r}=0, \tag{6.4}
\end{equation*}
$$

where $\mu \neq 0$.

Taking skew-symmetric part of (6.3), using the commutation formula exhibited by (1.6) for $v^{i}$ and (6.4), we get

$$
\begin{equation*}
\dot{\partial}_{j}\left(\mu_{k} v^{i}\right)=0 . \tag{6.5}
\end{equation*}
$$

Transvecting (6.5) by $y^{k}$ and putting $\mu=\mu_{s} y^{s}$, we get

$$
\begin{equation*}
\mu_{j}=\dot{\partial}_{j} \mu \tag{6.6}
\end{equation*}
$$

Taking skew-symmetric part of (6.1) and using the commutation formula exhibited by (1.7) for $v^{i}$, we get

$$
\begin{equation*}
N_{r j k}^{i} v^{r}=\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i} \tag{6.7}
\end{equation*}
$$

In view of (1.19), (6.4) and (6.7), equ. (6.2) becomes

$$
\begin{equation*}
\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}=0 \tag{6.8}
\end{equation*}
$$

Using (6.7) in (6.8), we get

$$
\begin{equation*}
N_{r j k}^{i} v^{r}=0 \tag{6.9}
\end{equation*}
$$

Thus, we see that the condition (6.8) is necessary consequence of a recurrent affine motion. Now, we shall establish that condition (6.8) is sufficient for (2.1d) to be an affine motion. To prove this, let us consider (6.8) holds.

Taking skew-symmetric part of (6.8), we get

$$
\begin{equation*}
\mathcal{B}_{j} \mu_{k}-\mathcal{B}_{k} \mu_{j}=0 \tag{6.10}
\end{equation*}
$$

Transvecting (4.1) by $y^{j}$ and using (1.5), we get

$$
\begin{equation*}
U_{r k h}^{i} y^{j} \mathcal{B}_{j} v^{r}=0 \tag{6.11}
\end{equation*}
$$

In view of (2.1d) and putting $\mu=\mu_{j} y^{j}$, equ. (6.11) becomes
(6.12) $\quad U_{r k h}^{i} v^{r}=0$,
where $\mu \neq 0$.

In view of (6.8), (6.9) and (6.12), equ. (6.2) becomes
(6.13) $\quad L_{v} \Pi_{j k}^{i}=0$.

Hence, the transformation considered is an affine motion.

Thus, we conclude

Theorem 6.1. The condition (6.8) is necessary and sufficient for an infinitesimal transformation generated by a recurrent vector $v^{i}\left(x^{j}\right)$ characterized by (2.1d) to be an affine motion.

## 7. Torse Forming Affine Motion

Let us consider an infinitesimal transformation generated by concurrent vector $v^{i}\left(x^{j}\right)$ characterized by (2.1e).

Differentiating (2.1e) covariantly with respect to $x^{j}$ in the sense of Berwald, we get

$$
\begin{equation*}
\mathcal{B}_{j} \mathcal{B}_{k} v^{i}=\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i}+\rho \mu_{k} \delta_{j}^{i}+\rho_{j} \delta_{k}^{i}, \tag{7.1}
\end{equation*}
$$

where $\rho_{j}=\mathcal{B}_{j} \rho$.

Taking skew-symmetric part of (7.1) and using the commutation formula exhibited by (1.7) for $v^{i}$, we get
(7.2) $\quad N_{r j k}^{i} v^{r}=\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i}+\rho \mu_{k} \delta_{j}^{i}+\rho_{j} \delta_{k}^{i}$.

In view of (1.15), (1.19), (2.1e), putting $\mu=\mu_{s} y^{s}$, using (7.2) and (1.5), we get

$$
\begin{equation*}
-\mu U_{r j k}^{i} v^{r}+2 N_{r j k}^{i} v^{r}=0 \tag{7.3}
\end{equation*}
$$

Transvecting (4.1) by $y^{j}$ and using (1.5), we get
(7.4) $\quad U_{r k h}^{i} y^{j} \mathcal{B}_{j} v^{r}=0$.

In view of (2.1e), putting $\mu=\mu_{j} y^{j}$ and (1.5) in (7.4), we get
(7.5) $\quad \mu U_{r k h}^{i} v^{r}=0$.

Using (7.5) in (7.3), we get

$$
\begin{equation*}
N_{r j k}^{i} v^{r}=0 \tag{7.6}
\end{equation*}
$$

In view of (1.15), (7.1),(7.2), (7.5) and (7.6), we get

$$
\begin{equation*}
L_{v} \Pi_{j k}^{i}=0 \tag{7.7}
\end{equation*}
$$

Hence, the transformation considered is an affine motion.

Thus, we conclude

Theorem 7.1. The conditions (7.5) and (7.6) are necessary and sufficient for an infinitesimal transformation generated by a recurrent vector $v^{i}\left(x^{j}\right)$ characterized by (2.1e) to be an affine motion.

## 8. Projective Motion of a Recurrent Finsler Space

The infinitesimal transformation (1.10) defines a projective motion if it transforms a system of geodesics of $F_{n}$ into geodesics $\overline{F_{n}}$. A necessary and sufficient condition that the infinitesimal transformation (1.10) defines a projective motion [16] which characterized by condition (1.20).

For some homogeneous scalar function P of degree one in $y^{i}$. For the homogeneity of $P_{h}$, it satisfies

$$
\begin{equation*}
P_{h} y^{h}=P . \tag{8.1}
\end{equation*}
$$

Also, Lie-derivative of the hv-curvature tensor $U_{j k h}^{i}$ in such projective motion may calculated by differentiating (1.20) partially with respect to $y^{j}$, using the commutation formula exhibited by (1.17) for $\Pi_{j k}^{i}$ and in view of remark 1.1., we get

$$
\begin{equation*}
L_{v} U_{j k h}^{i}=\delta_{k}^{i} P_{j h}+\delta_{h}^{i} P_{j k} \tag{8.2}
\end{equation*}
$$

where

$$
\begin{equation*}
P_{j l}=\dot{\partial}_{j} P_{l} \tag{8.3}
\end{equation*}
$$

for the homogeneity of $P_{j l}$, it satisfies
(8.4) $\quad P_{j l} y^{l}=0$.

Now, the projective motion becomes an affine motion, the condition
(8.5) $\quad L_{v} \Pi_{j k}^{i}=0$
holds.
proof

Let us consider a Finsler space characterized by (8.5).

In view of (8.5) and (1.20), we get

$$
\begin{equation*}
\delta_{k}^{i} P_{h}+\delta_{h}^{i} P_{k}=0 \tag{8.6}
\end{equation*}
$$

Contracting the indies i and k in (8.6), we get

$$
\begin{equation*}
(n+1) P_{h}=0 \tag{8.7}
\end{equation*}
$$

which implies
(8.8) $\quad P_{h}=0$.

Conversely, if (8.8) is true, the equ. (1.20) reduces to $L_{v} \Pi_{j k}^{i}=0$. The condition (8.8) is the necessary and sufficient condition for the infinitesimal transformation (1.20), which defines a projective motion to be an affine motion.

Also, the projective motion becomes an affine motion, the condition

$$
\begin{equation*}
L_{v} U_{j k h}^{i}=0 \tag{8.9}
\end{equation*}
$$

holds.
proof

Let us consider a Finsler space characterized by (8.9).

In view of (8.9) and (8.2), we get

$$
\begin{equation*}
\delta_{k}^{i} P_{h j}+\delta_{h}^{i} P_{j k}=0 . \tag{8.10}
\end{equation*}
$$

Contracting the indies i and k in (8.10), we get

$$
\begin{equation*}
(n+1) P_{h j}=0 \tag{8.11}
\end{equation*}
$$

which implies
(8.12) $\quad P_{h j}=0$.

Conversely, if (8.12) is true, the equ. (8.2) reduces to $L_{v} U_{j k h}^{i}=0$. The condition (8.12) is the necessary and sufficient condition for the infinitesimal transformation (8.2), which defines a projective motion to be an affine motion.

Definition 8.1. A recurrent Finsler space characterized by (1.8) in which the infinitesimal transformation (1.19) defines a projective motion, is called projective recurrent Finsler space briefly denoted by $U R-P \bar{F}_{n}$.

Applying Lie- operator to (1.8) and using (8.2), we get

$$
\begin{equation*}
L_{v} \mathcal{B}_{m} U_{j k h}^{i}=\left(L_{v} \lambda_{m}\right) U_{j k h}^{i}+\lambda_{m}\left(\delta_{k}^{i} P_{h j}+\delta_{h}^{i} P_{j k}\right) . \tag{8.13}
\end{equation*}
$$

Thus, we conclude

Theorem 8.1. In an $U R-P \bar{F}_{n}$, which admits projective motion, the equ. (8.13) holds.

In view of (8.12) and (8.13), we get

$$
\begin{equation*}
L_{v} \mathcal{B}_{m} U_{j k h}^{i}=\left(L_{v} \lambda_{m}\right) U_{j k h}^{i} . \tag{8.14}
\end{equation*}
$$

Thus, we conclude

Theorem 8.2. In an $U R-P \bar{F}_{n}$, if the projective motion becomes an affine motion , the equ. (8.14) is necessarily true.

In view of the commutation formula exhibited by (1.16) for the hv- curvature tensor $U_{j k h}^{i}$, (1.19) and (8.9), we
get
(8.15) $\quad L_{v} \mathcal{B}_{m} U_{j k h}^{i}=0$.

Since the projective motion becomes an affine motion in $U R-P \bar{F}_{n}$, in view of (8.14) and (8.15), we get
(8.16) $\quad L_{v} \lambda_{m}=0$
since $\bar{F}_{n}$ is non- flat space.

Thus, we conclude

Theorem 8.3. In an UR-P $\bar{F}_{n}$, if the projective motion becomes an affine motion, the recurrence vector field $\lambda_{m}$ satisfies the identity (8.16).

Differentiating (8.16) partially with respect to $y^{s}$, we get

$$
\begin{equation*}
\dot{\partial}_{s} L_{v} \lambda_{m}=0 . \tag{8.17}
\end{equation*}
$$

In view of the commutation formula exhibited by (1.17) for $\lambda_{m}$ and (8.17), we get

$$
\begin{equation*}
L_{v} \dot{\partial}_{s} \lambda_{m}=0 \tag{8.18}
\end{equation*}
$$

since $\bar{F}_{n}$ is non- flat space.

Thus, we conclude

Theorem 8.4. In an $U R-P \bar{F}_{n}$, if the projective motion becomes an affine motion, the recurrence vector field $\lambda_{m}$ satisfies the identity (8.18).

## 9. Special Projective Motion of a Recurrent Finsler Space

Let us consider a Finsler space admits a concurrent projective motion characterized by (2.1b).

Differentiating (2.1b) covariantly with respect to $x^{j}$ in the sense of Berwald, taking skew-symmetric part of the obtained equation and using the commutation formula exhibited by (1.7) for $v^{i}$, we get
(9.1) $\quad N_{h j k}^{i} v^{h}=0$.

In view of (1.17) and (1.20), we get

$$
\begin{equation*}
\mathcal{B}_{j} \mathcal{B}_{k} v^{i}-U_{r j k}^{i} y^{s} \mathcal{B}_{s} v^{r}+N_{r j k}^{i} v^{r}=\delta_{j}^{i} P_{k}+\delta_{k}^{i} P_{j} \tag{9.2}
\end{equation*}
$$

Using (2.1b) and (9.1) in (9.2), we get

$$
\begin{equation*}
-c U_{r k h}^{i} y^{r}=\delta_{k}^{i} P_{h}+\delta_{h}^{i} P_{k} \tag{9.3}
\end{equation*}
$$

Differentiating (9.3) covariantly with respect to $x^{m}$ and using the fact ( $\mathcal{B}_{m} y^{r}=0$ ), we get
(9.4) $\quad-c y^{r} \mathcal{B}_{m} U_{r k h}^{i}=\delta_{k}^{i} \mathcal{B}_{m} P_{h}+\delta_{h}^{i} \mathcal{B}_{m} P_{k}$.

Using (1.8) and (9.3) in (9.4), we get

$$
\begin{equation*}
\delta_{k}^{i}\left(\mathcal{B}_{m} P_{h}-\lambda_{m} P_{h}\right)+\delta_{h}^{i}\left(\mathcal{B}_{m} P_{k}-\lambda_{m} P_{k}\right)=0 . \tag{9.5}
\end{equation*}
$$

Contracting the indies i and k in (9.5), we get

$$
\begin{equation*}
\mathcal{B}_{m} P_{h}=\lambda_{m} P_{h} \tag{9.6}
\end{equation*}
$$

Thus, we conclude

Theorem 9.1. In an $U R-P \bar{F}_{n}$, which admits projective motion, if the vector filed $v^{i}\left(x^{j}\right)$ spans concurrent field, then the scalar function $P$ is recurrent.

If we adopt the similar process for (2.1c), we get the following theorem

Theorem 9.2. In an UR- $P \bar{F}_{n}$, which admits projective motion, if the vector filed $v^{i}\left(x^{j}\right)$ spans special concircular field, then the scalar function $P$ is recurrent.

Let us consider a Finsler space admits a special concircular projective motion characterized by (2.1c).

Differentiating (2.1c) covariantly with respect to $x^{j}$ in the sense of Berwald, taking skew-symmetric part of the obtained equation and using the commutation formula exhibited by (1.7) for $v^{i}$, we get

$$
\begin{equation*}
N_{h j k}^{i} v^{h}=\rho_{j} \delta_{k}^{i}, \tag{9.7}
\end{equation*}
$$

where $\rho_{j}=\mathcal{B}_{j} \rho$.

In view of (1.15), (1.20) , (2.1c), (9.7) and (1.5), we get

$$
\begin{equation*}
2 \rho_{j} \delta_{k}^{i}=\delta_{j}^{i} P_{k}+\delta_{k}^{i} P_{j} \tag{9.8}
\end{equation*}
$$

Transvecting (9.8) by $v^{j}$, we get

$$
\begin{equation*}
2 \rho_{j} v^{j} \delta_{k}^{i}=v^{i} P_{k}+\delta_{k}^{i} P_{j} v^{j} \tag{9.9}
\end{equation*}
$$

Contracting the indies $i$ and $k$ in (9.9), we get

$$
\begin{equation*}
2 n \rho_{j} v^{j}=(n+1) P_{j} v^{j} \tag{9.10}
\end{equation*}
$$

Transvecting (9.9) by $v^{k}$, we get
(9.11) $\quad \rho_{j} v^{j}=P_{j} v^{j}$.

In view of (9.10) and (9.11), we get
(9.12) $\quad P_{j} v^{j}=0=\rho_{j} v^{j}$.

Using (9.12) in (9.9), we get
(9.13) $\quad P_{k}=0$.

In view of (9.8) and (9.13), we get
(9.14) $\quad \rho_{j} \delta_{k}^{i}=0$.

Transvecting (9.14) by $y^{k}, y_{i}$ successively and using that fact $\left(y^{i} y_{i}=F^{2}\right)$, we get
(9.15) $\quad \rho_{j}=0$
i. e. $\rho$ is a covariant constant, a contradiction.

Thus, we conclude

Theorem 9.3. A Finsler space does not admit any special concircular projective motion.

Let us consider a Finsler space admits a recurrent projective motion characterized by (2.1d).
P. N. Pandy [7], proved that, if $v^{i}\left(x^{j}\right)$ are components of a non-null vector, then the equation
(9.16) $a v^{i}+b y^{i}=0$
implies $\mathrm{a}=\mathrm{b}=0$.

Differentiating (2.1d) covariantly with respect to $x^{j}$ in the sense of Berwald, taking skew-symmetric part of the obtained equation, using the commutation formula exhibited by (1.7) for $v^{i}$ and (2.1d), we get
and using (1.7), we get

$$
\begin{equation*}
N_{h j k}^{i} v^{h}=\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i} \tag{9.17}
\end{equation*}
$$

Transvecting (4.1) by $y^{j}$ and using (1.5), we get

$$
\begin{equation*}
U_{r k h}^{i} y^{j} \mathcal{B}_{j} v^{r}=0 \tag{9.18}
\end{equation*}
$$

In view of (2.1d) and putting $\mu=\mu_{j} y^{j}$ in (9.18), we get
(9.19) $\quad \mu U_{r k h}^{i} v^{r}=0$.

In view of (1.15), (2.1d), (9.17), (9.19) and (1.20), we get

$$
\begin{equation*}
2\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i}=\delta_{j}^{i} P_{k}+\delta_{k}^{i} P_{j} \tag{9.20}
\end{equation*}
$$

Transvecting (9.20) by $y^{k}$ and $y^{j}$ successively, using $\mu=\mu_{l} y^{l}$, the fact $\left(\mathcal{B}_{k} y^{j}=0\right)$ and (8.1), we get
(9.21) $\quad\left\{y^{j}\left(\mathcal{B}_{j} \mu\right)+\mu^{2}\right\} v^{i}=P y^{i}$.

In view of (9.16) and (9.21), we get
a) $y^{j} \mathcal{B}_{j} \mu=-\mu^{2} \quad$ and
b) $P=0$.

Thus, we conclude

Theorem 9.4. If a Finsler space admits a recurrent projective motion, the vector filed $v^{i}\left(x^{j}\right)$ satisfies (9.22a) and (9.22b).

Transvecting (9.20) by $v^{j}$, we get

$$
\begin{equation*}
2\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}\right) v^{i} v^{j}=v^{i} P_{k}+\delta_{k}^{i} P_{j} v^{j} \tag{9.23}
\end{equation*}
$$

In view of (1.12), (2.1d) and putting $\mu=\mu_{s} y^{s}$, Lie derivative of the vector $\mu_{k}$ is given by

$$
\begin{equation*}
L_{v} \mu_{k}=v^{j}\left(\mathcal{B}_{j} \mu_{k}+\mu_{j} \mu_{k}+\mu \dot{\partial}_{j} \mu_{k}\right) \tag{9.24}
\end{equation*}
$$

Differentiating (2.1d) partially with respect to $y^{j}$, we get

$$
\begin{equation*}
\dot{\partial}_{j} \mathcal{B}_{k} v^{i}=\dot{\partial}_{j}\left(\mu_{k} v^{i}\right) \tag{9.25}
\end{equation*}
$$

Taking skew-symmetric part of (9.25), using the commutation formula exhibited by (1.6) for $v^{i}$, (2.1d) and (9.19), we get

$$
\begin{equation*}
\dot{\partial}_{j}\left(\mu_{k} v^{i}\right)=0 . \tag{9.26}
\end{equation*}
$$

Transvecting (9.26) by $y^{k}$ and putting $\mu=\mu_{k} y^{k}$, we get

$$
\begin{equation*}
\mu_{j}=\dot{\partial}_{j} \mu \tag{9.27}
\end{equation*}
$$

Transvecting (9.24) by $y^{k}$, using (1.13a), (9.27) and putting $\mu=\mu_{k} y^{k}$, we get

$$
\begin{equation*}
L_{v} \mu=v^{j}\left(\mathcal{B}_{j} \mu+\mu \mu_{j}\right) \tag{9.28}
\end{equation*}
$$

In view of (9.28) and (1.13a), we get

$$
\begin{equation*}
\mathcal{B}_{j} \mu+\mu \mu_{j}=0 \tag{9.29}
\end{equation*}
$$

Transvecting (9.23) by $y^{k}$, using the fact $\left(\mathcal{B}_{j} y^{k}=0\right)$, putting $\mu=\mu_{k} y^{k}$, (8.1) and (9.29), we get
(9.30) $\quad P v^{i}+y^{i} P_{j} v^{j}=0$.

In view of (9.16) and (9.30), we get
(9.31)
a) $P=0$
and
b) $P_{j} v^{j}=0$.

Thus, we conclude

Theorem 9.5. The conditions (9.31a) and (9.31b) are necessary and sufficient for a recurrent projective motion to be an affine motion in a Finsler space.

Transvecting (9.23) by $y^{k}$, putting $\mu=\mu_{k} y^{k}$, using (8.3) and (9.28), we get

$$
\begin{equation*}
\left(2 L_{v} \mu-P\right) v^{i}=P_{j} v^{j} y^{i} . \tag{9.32}
\end{equation*}
$$

In view of (9.16) and (9.32), we get
a) $2 L_{v} \mu=P$ and
b) $P_{j} v^{j}=0$.

Transvecting (9.20) by $y^{k}$, putting $\mu=\mu_{k} y^{k}$ and (8.1), we get
(9.34) $\quad 2\left(\mathcal{B}_{j} \mu+\mu \mu_{j}\right) v^{i}=\delta_{j}^{i} P+P_{j} y^{i}$.

Contracting the indies $i$ and $j$ in (9.34), using (9.29) and (8.1), we get

$$
\begin{equation*}
P=0 \tag{9.35}
\end{equation*}
$$

Thus, we conclude

Theorem 9.6. The condition (9.35) is necessary and sufficient for a recurrent projective motion to be an affine motion in a Finsler space.

## 10. Conclusion

(10.1) Every contra vector generates an affine motion in a Finsler space.
(10.2) In an $U R-F_{n}$, if any contra vector $v^{i}\left(x^{j}\right)$ generates an infinitesimal transformation, it must be orthogonal to the recurrence vector.
(10.3) In an $U B R-F_{n}$, if any contra vector $v^{i}\left(x^{j}\right)$ generates an infinitesimal transformation, then the recurrence tensor $\mathrm{a}_{\mathrm{lm}}$ satisfies conditions (3.9a) and (3.9b).
(10.4) If a Finsler space admits an infinitesimal transformation generated by a concurrent vector , then the transformation is necessarily an affine motion.
(10.5) If a Finsler space admits an infinitesimal transformation generated by a concurrent vector, then the hvcurvature tensor $\mathrm{U}_{\mathrm{jkh}}^{\mathrm{i}}$ satisfies (4.2) and (4.3).
(10.6) A Finsler space does not admit any special concircular affine motion.
(10.7) In an UR- $\mathrm{P} \overline{\mathrm{F}}_{\mathrm{n}}$, if the projective motion becomes an affine motion.
(10.8) In an UR- $\mathrm{P} \overline{\mathrm{F}}_{\mathrm{n}}$, if the projective motion becomes an affine motion, the recurrence vector field $\lambda_{\mathrm{m}}$ satisfies the identity (8.16).
(10.9) In an UR- $\overline{\mathrm{F}}_{\mathrm{n}}$, if the projective motion becomes an affine motion, the recurrence vector field $\lambda_{\mathrm{m}}$ satisfies the identity (8.18).
(10.10) In an UR- $\mathrm{P} \overline{\mathrm{F}}_{\mathrm{n}}$, which admits projective motion, if the vector filed $\mathrm{v}^{\mathrm{i}}\left(\mathrm{x}^{\mathrm{j}}\right)$ spans concurrent field, then the scalar function P is recurrent.
(10.11) A Finsler space does not admit any special concircular projective motion.
(10.12) If a Finsler space admits a recurrent projective motion, the vector filed $\mathrm{v}^{\mathrm{i}}\left(\mathrm{x}^{\mathrm{j}}\right)$ satisfies (9.22a) and (9.22b).

## 11. Recommendations

The authors recommend the research should be continued in the motions.

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